

Part Two: Marking Instructions for each Question

Section A

| Question | | Expected Answer(s) | Max Mark | Additional Guidance |
|----------|---|--|----------|--|
| A | 1 | $I = Ft = mv - mu$ $3(4) = 2v - 0$ $v = 6\text{ms}^{-1}$ <p>Conservation of Linear Momentum:</p> $m u_1 + m_2 u_2 = (m_1 + m_2)v$ $2(6) + m(0) = (2 + m)(3.75)$ $m = \frac{12}{3.75} - 2 = 1.2\text{ kg}$ <p><u>ALTERNATIVE SOLUTION</u></p> $F = ma$ $3 = 2a$ $a = \frac{3}{2}\text{ m s}^{-2}$ $u = 0 \quad t = 4 \quad a = \frac{3}{2}$ $v = u + at$ $= 0 + \frac{3}{2}(4) = 6\text{ m s}^{-1}$ <p>Conservation of Linear Momentum:</p> $m u_1 + m_2 u_2 = (m_1 + m_2)v$ $2(6) + m(0) = (2 + m)(3.75)$ $m = \frac{12}{3.75} - 2 = 1.2\text{ kg}$ | 4 | <p>M1: Use of impulse to calculate velocity of impact</p> <p>E1: Value for velocity of impact</p> <p>M1: Conservation of Linear Momentum</p> <p>E1: Value of m</p> <p>M1: Use of Newton's 2nd Law to calculate acceleration</p> <p>E1: Stuva to calculate velocity of P before impact</p> <p>M1: Conservation of Linear Momentum</p> <p>E1: Value of m</p> |

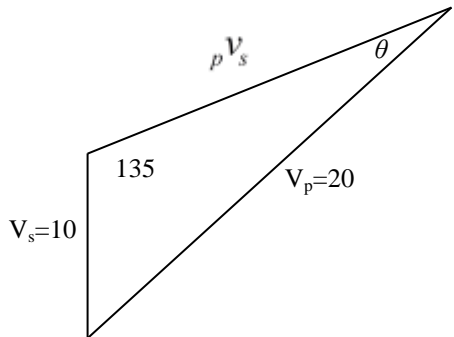
| Question | | Expected Answer(s) | Max Mark | Additional Guidance |
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| A | 2 | $T = \frac{2\pi}{\omega} \Rightarrow \frac{2\pi}{\omega} = \frac{14\pi}{5} \Rightarrow \omega = \frac{5}{7}$ $v^2 = \omega^2(a^2 - x^2)$ $2 \cdot 5^2 = \frac{25}{49}(a^2 - 1 \cdot 2^2)$ $\frac{2 \cdot 5^2 \times 49}{25} + 1 \cdot 2^2 = a^2$ $a = 3.7 \text{ metres}$ $x = A \sin \omega t$ $1.2 = 3.7 \sin\left(\frac{5t}{7}\right)$ $t = 0.46 \text{ seconds}$ | 4 | <p>E1: Value of ω</p> <p>M1: Correct formula for velocity and amplitude and correct substitution</p> <p>E1: Value for amplitude</p> <p>M1: Use of formula to find displacement and answer</p> |

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|----------|---|------|--|----------|---|
| A | 3 | (i) | | 2 | |
| | | (ii) | $W = \int_0^{200} (F - 500)dx$ $= \int_0^{200} (3000 - 15x - 500)dx$ $= \left[2500x - \frac{15x^2}{2} \right]_0^{200}$ $= 200000 \text{ J} = 200 \text{ kJ}$ <p>Work- Energy Principle:</p> $W = \frac{1}{2}mv^2 - \frac{1}{2}mu^2$ $200000 = \frac{1}{2} \times 700v^2$ $v = 23.9 \text{ m s}^{-1}$ <p><i>Alternative solution for (ii)</i></p> $F = ma \Rightarrow a = \frac{F}{m}$ $v \frac{dv}{dx} = \frac{1}{700} \int (2500 - 15x)dx$ $F = ma$ $v \frac{dv}{dx} = \frac{1}{700} (2500 - 15x)$ $\int v dv = \frac{1}{700} \int (2500 - 15x)dx$ $\frac{v^2}{2} = \frac{1}{700} \left[2500x - \frac{15x^2}{2} \right]_0^{200}$ $v = 23.9 \text{ ms}^{-1}$ | 2 | <p>M1: Method of finding work done $\int F dx$ (with limits or calculation of constant included later)</p> <p>E1: Correct answer</p> <p>M1: Use of Work – Energy Principle and substitution</p> <p>E1: Correct calculation of speed</p> <p>M1: Use of correct differential equation and substitution</p> <p>E1: Correct calculation of speed</p> |

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| A | 4 | <p>↑ Equilibrium $2T \cos 30^\circ + T \cos 50^\circ = 2g$</p> $2T \cos 30^\circ + T \cos 50^\circ = 2g$ $T = \frac{2g}{2 \cos 30^\circ + \cos 50^\circ} = 8.25N$ $2T = 16.5N$ <p>→ $F = \frac{mv^2}{r}$</p> $2T \sin 30^\circ + T \sin 50^\circ = \frac{2v^2}{r}$ $\tan 50^\circ = \frac{r}{0.3} \quad r = 0.358$ $2T \sin 30^\circ + T \sin 50^\circ = \frac{2v^2}{0.358}$ $2v^2 = 0.358(16.5 \times \frac{1}{2} + 8.25 \times 0.766)$ $v = 1.61 \text{ m s}^{-1}$ | 6 | <p>M1: Consider equilibrium involving both tensions and weight</p> <p>E1: Correct substitution of components</p> <p>E1: Using conditions to find tension</p> <p>M1: Horizontal use of $F = \frac{mv^2}{r}$ (Consistent with M1 above)</p> <p>E1: Calculation of radius of circle</p> <p>E1: Algebraic manipulation to find v</p> |
| <p>Note: If angular speed used can achieve 3/4.</p> | | | | |

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| A | 5 | <p>Perpendicular to slope: $R = Mg \cos \theta = \frac{4Mg}{5}$</p> <p>Along slope: $F = ma$</p> $-\mu R - Mg \sin \theta = Ma$ $\frac{-4Mg}{4 \times 5} - \frac{3Mg}{5} = Ma$ $a = \frac{-4g}{5} (= -7.84)$ <p>Motion under constant acceleration up slope to rest:</p> $v^2 = u^2 + 2as$ $0 = u^2 - \frac{8gs}{5}$ $s = \frac{5u^2}{8g}$ <p>Consider motion down slope: $F = ma$</p> $Mg \sin \theta - \frac{Mg \cos \theta}{4} = Ma$ $a = \frac{2g}{5} (= 3.92)$ <p>Constant acceleration down slope:</p> $v^2 = u^2 + 2as$ $4u^2 = \frac{4gs}{5}$ $s = \frac{5u^2}{g}$ <p>Distance $AC = \frac{5u^2}{g} - \frac{5u^2}{8g} = \frac{35u^2}{8g}$</p> | 6 | <p>M1: Equilibrium perpendicular to slope with equation</p> <p>M1: $F = ma$ along slope with equation</p> <p>E1: Calculation of acceleration</p> <p>E1: Calculation of displacement up slope to rest</p> <p>E1: Calculation of acceleration down slope</p> <p>E1: Calculation of displacement down slope and distance AC</p> |

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| A | 6 | <p>Method 1:</p> $r_p = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad r_s = \begin{pmatrix} 15 \cos 45^\circ \\ 15 \sin 45^\circ \end{pmatrix}$ $v_p = \begin{pmatrix} 20 \cos \theta \\ 20 \sin \theta \end{pmatrix} \quad v_s = \begin{pmatrix} 0 \\ 10 \end{pmatrix}$ <p>After time t</p> $r_p = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} 20 \cos \theta \\ 20 \sin \theta \end{pmatrix} = \begin{pmatrix} 20t \cos \theta \\ 20t \sin \theta \end{pmatrix}$ $r_s = \begin{pmatrix} 15 \cos 45^\circ \\ 15 \sin 45^\circ \end{pmatrix} + t \begin{pmatrix} 0 \\ 10 \end{pmatrix} = \begin{pmatrix} 10.6 \\ 10.6 + 10t \end{pmatrix}$ <p>At interception $r_p = r_s$ $20t \cos \theta = 10.6$ and $20t \sin \theta = 10.6 + 10t$ $t = \frac{10.6}{20 \cos \theta}$ $t = \frac{10.6}{20 \sin \theta - 10}$ $20 \sin \theta - 10 = 20 \cos \theta$ $\sin \theta - \cos \theta = \frac{1}{2}$ $\sqrt{2} \sin(\theta - 45^\circ) = \frac{1}{2}$ $\theta = 65.7^\circ \Rightarrow$ patrol vessel should steer on bearing 024.3°</p> $t = \frac{10.6}{20 \cos 65.7} = 1.28 \text{ hours} = 1 \text{ hour } 17 \text{ min}$ <p>Interception occurs at 4:17pm</p> | 6 | <p>M1: Statements of displacements and velocity vectors at 3pm</p> <p>E1: Statements of displacements after t hours</p> <p>M1: Equate components</p> <p>E1: Algebraic manipulation</p> <p>E1: Interpret answer to state bearing of interception</p> <p>E1: Calculation of time</p> |

| Question | Expected Answer(s) | Max Mark | Additional Guidance |
|-------------------|---|----------|--|
| <p>A 6</p> | <p>(cont)</p> <p>Method 2:</p> <p>${}_pV_s$ must be in the direction <i>PS</i> for interception</p>  $\frac{20}{\sin 135} = \frac{10}{\sin \theta}$ $\theta = \sin^{-1} \frac{10 \sin 135}{20} = 20.7^\circ$ <p>Patrol vessel must sail $(180 - 155.7) = 24.3^\circ$</p> $v^2 = 10^2 + 20^2 - 2 \times 10 \times 20 \times \cos 24.3$ $v = 11.6$ $t = \frac{15}{11.6} = 1 \text{ hour } 17 \text{ mins}$ <p>Interception occurs at 4:17pm</p> | | <p>M1: For interception, relative velocity vector in direction <i>PS</i></p> <p>M1: Correct diagram annotated</p> <p>E1: Use of trig</p> <p>E1: Interpret answer to state direction of interception</p> <p>E1: Find relative velocity</p> <p>E1: Calculation of time</p> |

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|------------|---|----------|--|
| A 6 | <p>(cont)</p> <p>Method 3:</p> $v_P = \begin{pmatrix} 20 \cos \theta \\ 20 \sin \theta \end{pmatrix} \quad v_s = \begin{pmatrix} 0 \\ 10 \end{pmatrix}$ ${}_P v_s = v_P - v_s = \begin{pmatrix} 20 \cos \theta \\ 20 \sin \theta - 10 \end{pmatrix}$ <p>${}_P v_s$ must be in the direction PS for interception</p> $\begin{pmatrix} 20 \cos \theta \\ 20 \sin \theta - 10 \end{pmatrix} = k \begin{pmatrix} \cos 45^\circ \\ \sin 45^\circ \end{pmatrix}$ $k \cos 45 = 20 \cos \theta$ $k \sin 45 = 20 \sin \theta - 10$ $1 = \frac{20 \sin \theta - 10}{20 \cos \theta} \Rightarrow 20 \cos \theta = 20 \sin \theta - 10$ $\sin \theta - \cos \theta = \frac{1}{2}$ $\sqrt{2} \sin(\theta - 45)^\circ = \frac{1}{2}$ $\theta = 65.7^\circ \Rightarrow \text{patrol vessel should}$ <p style="text-align: center;">steer on bearing 024.3°</p> $t = \frac{10.6}{20 \cos 65.7} = 1.28 \text{ hours} = 1 \text{ hour } 17 \text{ min}$ <p>Interception occurs at 4:17pm</p> | | <p>M1: Statement of condition for interception</p> <p>E1: Expression for relative velocity vector</p> <p>M1: Equate components</p> <p>E1: Algebraic manipulation</p> <p>E1: Interpret answer to state bearing of interception</p> <p>E1: Calculation of time</p> |

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| A 7 | $a_L = \frac{1}{9}g \quad a_B = g$ \downarrow ${}_B a_L = g - \frac{1}{9}g = \frac{8g}{9}$ ${}_B v_L = \int {}_B a_L dt = \frac{8g}{9}t + c$ $t = 0, v = -3.5 \Rightarrow v = \frac{8g}{9}t - 3.5$ ${}_B r_L = \int {}_B v_L dt = \frac{4g}{9}t^2 - 3.5t + k$ $t = 0, r = -1 \Rightarrow {}_B r_L = \frac{4g}{9}t^2 - 3.5t - 1$ ${}_B r_L(t) = 0 \text{ when ball hits floor}$ $\frac{4g}{9}t^2 - 3.5t - 1 = 0$ $4gt^2 - 31.5t - 9 = 0$ $39.2t^2 - 31.5t - 9 = 0$ $t = \frac{31.5 \pm \sqrt{(-31.5)^2 - 4 \times 39.2 \times -9}}{78.4}$ $t = 1.03 \text{ or } t = -0.22$ $t = 1.03 \text{ seconds (reject negative answer)}$ | 7 | <p>M1: Find relative acceleration</p> <p>M1: Use of calculus to find relative velocity</p> <p>E1: Correct expression for relative velocity</p> <p>E1: Correct expression for relative displacement</p> <p>M1: Statement for conditions when ball hits floor of lift</p> <p>E1: Process of calculating time</p> <p>E1: Correct answer for time</p> |

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|---|---|---|--|--|---|
| A 7 | <p>(cont)</p> <p><u>Second solution using relative acceleration and stuva</u></p> $a_L = \frac{1}{9}g \quad a_B = g$ ${}_B a_L = g - \frac{1}{9}g = \frac{8g}{9}$ $s = 1 \quad t = \quad u = -3.5 \quad v = \quad a = \frac{8g}{9}$ $s = ut + \frac{1}{2}at^2 \quad 1 = -3.5t + \frac{4g}{9}t^2$ $4gt^2 - 31.5t - 9 = 0 \quad 39.2t^2 - 31.5t - 9 = 0$ $t = \frac{31.5 \pm \sqrt{(-31.5)^2 - 4 \times 39.2 \times -9}}{78.4}$ $t = 1.03 \text{ or } t = -0.22$ $t = 1.03 \text{ seconds (reject negative answer)}$ <p><u>Alternative solution</u></p> <table style="width: 100%; border: none;"> <tr> <td style="width: 50%; vertical-align: top;"> <p>Ball</p> $a = -g$ $v = -gt + c$ $t = 0 \quad v = 3.5 \Rightarrow c = 3.5$ $r = \frac{-gt^2}{2} + 3.5t + c_2$ $t = 0 \quad r = 0 \Rightarrow c_2 = 0$ $r = \frac{-gt^2}{2} + 3.5t$ $r_1 = r_2$ $\frac{-gt^2}{2} + 3.5t = \frac{-gt^2}{18} - 1 \Rightarrow 8gt^2 - 63t - 18 = 0$ $4gt^2 - 31.5t - 9 = 0 \quad 39.2t^2 - 31.5t - 9 = 0$ $t = \frac{31.5 \pm \sqrt{(-31.5)^2 - 4 \times 39.2 \times -9}}{78.4}$ $t = 1.03 \text{ or } t = -0.22 \Rightarrow$ $t = 1.03 \text{ seconds (reject negative answer)}$ </td> <td style="width: 50%; vertical-align: top;"> <p>Lift</p> $a = \frac{-g}{9}$ $v = \frac{-gt}{9} + k$ $t = 0 \quad v = 0 \Rightarrow k = 0$ $r = \frac{-gt^2}{18} + k_2$ $t = 0 \quad r = -1 \Rightarrow k_2 = -1$ $r = \frac{-gt^2}{18} - 1$ </td> </tr> </table> | <p>Ball</p> $a = -g$ $v = -gt + c$ $t = 0 \quad v = 3.5 \Rightarrow c = 3.5$ $r = \frac{-gt^2}{2} + 3.5t + c_2$ $t = 0 \quad r = 0 \Rightarrow c_2 = 0$ $r = \frac{-gt^2}{2} + 3.5t$ $r_1 = r_2$ $\frac{-gt^2}{2} + 3.5t = \frac{-gt^2}{18} - 1 \Rightarrow 8gt^2 - 63t - 18 = 0$ $4gt^2 - 31.5t - 9 = 0 \quad 39.2t^2 - 31.5t - 9 = 0$ $t = \frac{31.5 \pm \sqrt{(-31.5)^2 - 4 \times 39.2 \times -9}}{78.4}$ $t = 1.03 \text{ or } t = -0.22 \Rightarrow$ $t = 1.03 \text{ seconds (reject negative answer)}$ | <p>Lift</p> $a = \frac{-g}{9}$ $v = \frac{-gt}{9} + k$ $t = 0 \quad v = 0 \Rightarrow k = 0$ $r = \frac{-gt^2}{18} + k_2$ $t = 0 \quad r = -1 \Rightarrow k_2 = -1$ $r = \frac{-gt^2}{18} - 1$ | | <p>M1 Show understanding of motion under constant relative acceleration</p> <p>M1: Find relative acceleration</p> <p>M1 : Consider motion ↓ under constant relative acceleration</p> <p>E1: <i>stuva</i> and substitution</p> <p>E1: Correct quadratic equation</p> <p>E1: Process of calculating time</p> <p>E1: Correct answer for time</p> <p>M1 Vertical motion of ball and lift separately</p> <p>E1: Correct expression for displacement of lift/ball after t secs</p> <p>E1 : Correct expression for displacement of otherafter t secs</p> <p>M1: Equating displacements</p> <p>E1: Correct quadratic equation</p> <p>E1: Process of calculating time</p> <p>E1: Correct answer for time</p> |
| <p>Ball</p> $a = -g$ $v = -gt + c$ $t = 0 \quad v = 3.5 \Rightarrow c = 3.5$ $r = \frac{-gt^2}{2} + 3.5t + c_2$ $t = 0 \quad r = 0 \Rightarrow c_2 = 0$ $r = \frac{-gt^2}{2} + 3.5t$ $r_1 = r_2$ $\frac{-gt^2}{2} + 3.5t = \frac{-gt^2}{18} - 1 \Rightarrow 8gt^2 - 63t - 18 = 0$ $4gt^2 - 31.5t - 9 = 0 \quad 39.2t^2 - 31.5t - 9 = 0$ $t = \frac{31.5 \pm \sqrt{(-31.5)^2 - 4 \times 39.2 \times -9}}{78.4}$ $t = 1.03 \text{ or } t = -0.22 \Rightarrow$ $t = 1.03 \text{ seconds (reject negative answer)}$ | <p>Lift</p> $a = \frac{-g}{9}$ $v = \frac{-gt}{9} + k$ $t = 0 \quad v = 0 \Rightarrow k = 0$ $r = \frac{-gt^2}{18} + k_2$ $t = 0 \quad r = -1 \Rightarrow k_2 = -1$ $r = \frac{-gt^2}{18} - 1$ | | | | |

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| A | 8 | (a) (b) | 3 7 | |
| | | <p>At Q: total energy = $\frac{1}{2}mv^2 = 1.5u^2$</p> <p>At top of circle total energy:</p> $mgh + \frac{1}{2}mv^2$ $= 3g \times 1.8 + \frac{3}{2}v^2 = 5.4g + \frac{3}{2}v^2$ $1.5u^2 > 5.4g$ <p>For complete circles $v > 0$:</p> $u > \sqrt{\frac{18g}{5}} \text{ ms}^{-1}$ <p>Height at any time: $0.9(1 - \cos \theta)$</p> <p>At rest (maximum height):</p> <p>Energy = $mgh = 3g \times 0.9(1 - \cos \theta)$</p> <p>If $u = 4$: Energy at Q = $\frac{1}{2} \times 3 \times 4^2 = 24$</p> $24 = 3g \times 0.9(1 - \cos \theta)$ $\cos \theta = 0.093$ $\theta = 84.7^\circ$ <p>Angle of oscillation = 169.4°</p> <p>Maximum tension when $\theta = 0$</p> $T - 3g = \frac{mv^2}{r}$ <p>↑</p> $T = 3g + \frac{3 \times 4^2}{0.9} = 82.7 \text{ N}$ | | <p>M1: Consideration of conservation of energy.</p> <p>E1: Correct statements of energy at bottom and top of circle</p> <p>M1: For complete circles $v > 0$ and find u</p> <p>M1: General expression for height at any time</p> <p>M1: Energy when rod is at rest</p> <p>E1: Equate this with energy vertically below P</p> <p>E1: Solve trig equation to find angle of oscillation</p> <p>M1: Understanding of maximum tension (stated or implied)</p> <p>M1: Use of $F = \frac{mv^2}{r}$</p> <p>E1: Calculation of Tension</p> |

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|----------|---|---|----------|--|
| A | 9 | (a) | 3 3 | |
| | | <p>(i)</p> <p>(ii)</p> $v = \int a dt = \int 13 \left(\frac{3}{8} - \frac{t}{16} \right) dt = 13 \left(\frac{3}{8}t - \frac{t^2}{32} \right) + c$ $t = 0, 0 = 0 \Rightarrow c = 0$ $v = 13 \left(\frac{3}{8}t - \frac{t^2}{32} \right)$ $t = \frac{5}{2} : v = 13 \left(\frac{3}{8} \times \frac{5}{2} - \frac{\left(\frac{5}{2} \right)^2}{32} \right) = 9.65 \text{ ms}^{-1}$ <p>→: $R = 9.65 \cos 25^\circ \times t$</p> <p>↑: $s = ut + \frac{1}{2}at^2$</p> $0 = 9.65 \sin 25^\circ \times t - \frac{1}{2}gt^2$ $t(4.08 - 4.9t) = 0$ $t = 0 \text{ or } t = 0.83$ <p>→: $R = 9.65 \cos 25^\circ \times 0.83 = 7.26 \text{ metres}$</p> | | <p>M1: Integration to find expression for velocity</p> <p>E1: Substitution and correct expression</p> <p>E1: Substitute for t and correct answer for speed</p> <p>M1: Consider motion horizontally and vertically with substitution</p> <p>E1: Value of t</p> <p>E1: Value of R</p> |
| A | 9 | (b) | 3 2 | |
| | | <p>(i)</p> <p>(ii)</p> $\rightarrow 7.51 = 10.2 \cos \theta \times t \quad t = \frac{7.51}{10.2 \cos \theta}$ $\uparrow: s = ut + \frac{1}{2}t^2$ $0 = \frac{10.2 \sin \theta \times 7.51}{10.2 \cos \theta} - \frac{g}{2} \left(\frac{7.51}{10.2 \cos \theta} \right)^2$ $7.51 \tan \theta - 2.656 \dots \sec^2 \theta = 0$ $7.51 \tan \theta - 2.656 \dots \tan^2 \theta - 2.656 \dots = 0$ $\tan \theta = 2.41 \text{ or } \tan \theta = 0.41$ $\theta = 67.2^\circ \quad \theta = 22.3^\circ$ $\uparrow: v^2 = u^2 + 2as$ $s = 4.51 \text{ or } s = 0.76 \text{ m}$ <p>Athlete cannot jump 4.51m vertically ⇒ Take-off angle $\approx 22.3^\circ$</p> | | <p>M1: Consider motion → and expression for t</p> <p>M1: Consider motion vertically with this value of t and substitution</p> <p>E1: Solution of trig equation to give 2 angles of projection</p> <p>E1: Find two possible heights</p> <p>E1: Explanation of answer</p> |

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|----------|---|--|----------|---|
| A | 9 | (b) | | |
| | | <p>(cont)</p> <p>Method 2:</p> $\rightarrow 7.51 = 10 \cdot 2 \cos \theta \times t \quad t = \frac{7.51}{10 \cdot 2 \cos \theta}$ $\uparrow: s = ut + \frac{1}{2}t^2$ $0 = \frac{10 \cdot 2 \sin \theta \times 7.51}{10 \cdot 2 \cos \theta} - \frac{g}{2} \left(\frac{7.51}{10 \cdot 2 \cos \theta} \right)^2$ $\frac{7.51 \sin \theta}{\cos \theta} - \frac{2 \cdot 656 \dots}{\cos^2 \theta} = 0 \quad [\times \cos^2 \theta]$ $7.51 \sin \theta \cos \theta - 2 \cdot 656 \dots = 0$ $3 \cdot 755 \sin 2\theta - 2 \cdot 656 \dots = 0$ $\sin 2\theta = 0.707 \dots$ $2\theta = 45 \cdot 02 \dots \quad 2\theta = 134 \cdot 976 \dots$ $\theta = 22 \cdot 5^\circ \quad \theta = 67 \cdot 5^\circ$ $\uparrow: v^2 = u^2 + 2as$ $s = 4 \cdot 51 \text{ or } s = 0 \cdot 76m$ <p>Athlete cannot jump 4.51m vertically \Rightarrow Take-off angle $\approx 22 \cdot 5^\circ$</p> <p>Method 3 (equation of a trajectory):</p> $y = x \tan \theta - \frac{gx^2}{2u^2 \cos^2 \theta}$ $0 = 7.51 \tan \theta - \frac{g(7.51^2)}{2(10 \cdot 2^2) \cos^2 \theta}$ $7.51 \tan \theta - 2 \cdot 656 \dots \sec^2 \theta = 0$ $7.51 \tan \theta - 2 \cdot 656 \dots \tan^2 \theta - 2 \cdot 656 \dots = 0$ $\tan \theta = 2 \cdot 41 \text{ or } \tan \theta = 0 \cdot 41$ $\theta = 67 \cdot 2^\circ \quad \theta = 22 \cdot 3^\circ$ $\uparrow: v^2 = u^2 + 2as$ $s = 4 \cdot 51 \text{ or } s = 0 \cdot 76m$ <p>Athlete cannot jump 4.51m vertically \Rightarrow Take-off angle $\approx 22 \cdot 3^\circ$</p> | | <p>M1: Consider motion \rightarrow and expression for t</p> <p>M1: Consider motion vertically with this value of t and substitution</p> <p>E1: Solution of trig equation to give 2 angles of projection</p> <p>E1: Find two possible heights</p> <p>E1: Explanation of answer</p> <p>M1: Consider equation of trajectory.</p> <p>E1: When $y = 0$ $x = 7.51$ and $u = 10 \cdot 2$ arrange in suitable form and prepare to solve</p> <p>E1: Solution of trig equation to give 2 angles of projection</p> <p>E1: Find two possible heights</p> <p>E1: Explanation of answer</p> |

| Question | | Expected Answer(s) | Max Mark | Additional Guidance |
|----------|----|--|----------|---|
| A | 10 | $F = \frac{kmg}{v}$ $\frac{kmg}{v} - mg = mv \frac{dv}{dx}$ $v^2 \frac{dv}{dx} = g(k - v)$ $\int \frac{v^2}{k - v} dv = \int g dx$ $\frac{-v^2}{2} - kv - k^2 \ln k - v = gx + C$ $x = 0 \quad v = 0: -\frac{1}{2}(0^2) - k(0) - k^2 \ln k - 0 = 0 + C$ $\Rightarrow C = -k^2 \ln k $ $gx = k^2 \ln \left \frac{k}{k - v} \right - kv - \frac{1}{2}v^2$ <p>At height h: $v = u \Rightarrow gh = k^2 \ln \left \frac{k}{k - u} \right - ku - \frac{1}{2}u^2$</p> $mgh + \frac{1}{2}mu^2 = mk^2 \ln \left \frac{k}{k - u} \right - mku - \frac{mu^2}{2} + \frac{mu^2}{2}$ $= m \left[k^2 \ln \left \frac{k}{k - u} \right - ku \right]$ $\frac{m \left[k^2 \ln \left \frac{k}{k - u} \right - ku \right]}{mkg} = \frac{k}{g} \ln \left \frac{k}{k - u} \right - \frac{u}{g}$ | 2 8 | <p>M1: $F = \frac{P}{v}$ Connect power and force and substitution.</p> <p>E1: $F = ma$ and using $a = v \frac{dv}{dx}$</p> <p>M1: Integration to find displacement and separation of variables</p> <p>E1: Process of Integration</p> <p>E1: Substitution and simplification</p> <p>E1: Final substitution and expression processed</p> <p>M1: Work done = Change of energy</p> <p>E1: Algebraic manipulation</p> <p>M1: Time = $\frac{\text{Work}}{\text{Power}}$</p> <p>E1: Final manipulation</p> |

| Question | | Expected Answer(s) | Max Mark | Additional Guidance |
|----------|----|--|----------|---------------------|
| A | 10 | <p>(cont)</p> <p><i>Alternative for last 2 marks:</i></p> <p>Work done =</p> $\int_0^T Fv dt = \int_0^T \frac{kmg}{v} \times v dt = \int_0^T kmg dt = kmgT$ $kmgT = \frac{1}{2} mu^2 + mgh$ $= \frac{1}{2} mu^2 + m(k^2 \ln \left \frac{k}{k-u} \right - ku - \frac{1}{2} u^2)$ $T = \frac{k}{g} \ln \left \frac{k}{k-u} \right - \frac{u}{g}$ | | |

[END OF SECTION A]

Section B (Mathematics for Applied Mathematics)

| Question | | Expected Answer(s) | Max Mark | Additional Guidance |
|----------|----------|---|----------|---|
| B | 1 | $y = 2x\sqrt{x-1}$ $\frac{dy}{dx} = 2x \cdot \frac{d}{dx}(\sqrt{x-1}) + \sqrt{x-1} \times \frac{d}{dx}(2x)$ $= 2x \cdot \frac{1}{2}(x-1)^{-\frac{1}{2}} + \sqrt{x-1} \times 2$ <p>Gradient given by $\frac{dy}{dx}$ when $x = 10$,</p> $\text{Gradient} = 10 \cdot (9)^{-\frac{1}{2}} + \sqrt{9} \times 2$ $= \frac{28}{3}$ | 4 | <p>1 product rule</p> <p>1 first correct term</p> <p>1 second correct term</p> <p>1 evaluation (accept decimal equivalent to minimum of 3 sf)</p> |
| B | 2 | (a) $A + B = \begin{pmatrix} 4 & -7 & 6 \\ k-3 & 9 & -1 \\ 5 & 1 & 1 \end{pmatrix}$ | 1 | 1 evaluation |
| B | 2 | (b) $\det A = 1 \begin{vmatrix} 0 & -1 \\ 3 & 0 \end{vmatrix} - 3 \begin{vmatrix} k & -1 \\ 5 & 0 \end{vmatrix} + 4 \begin{vmatrix} k & 0 \\ 5 & 3 \end{vmatrix}$ $= 1(0 + 3) - 3(0 + 5) + 4(3k - 0)$ $= 12k - 12$ | 2 | <p>1 form of determinant</p> <p>1 evaluation</p> |
| B | 2 | (c) $BC = \begin{pmatrix} 3 & -10 & 2 \\ -3 & 9 & 0 \\ 0 & -2 & 1 \end{pmatrix} \begin{pmatrix} 3 & 2 & -6 \\ 1 & 1 & -2 \\ 2 & 2 & -1 \end{pmatrix}$ $= \begin{pmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{pmatrix}$ | 1 | 1 evaluation |
| B | 2 | (d) $BC = 3I.$ $B = 3C^{-1} \text{ or } C = 3B^{-1}$ | 2 | <p>1 identity matrix connection or mention of inverse</p> <p>1 relationship correct</p> |

| Question | | Expected Answer(s) | Max Mark | Additional Guidance |
|----------|----------|---|----------|---|
| B | 3 | $I = \int x \sin 3x dx$ $u = x \quad dv = \sin 3x$ $du = 1 \quad v = \int \sin 3x dx$ $= -\frac{1}{3} \cos 3x$ $I = x \cdot \frac{-1}{3} \cos 3x - \int 1 \cdot \frac{-1}{3} \cos 3x dx$ $= \frac{-x}{3} \cos 3x + \frac{1}{3} \int \cos 3x dx$ $= \frac{-x}{3} \cos 3x + \frac{1}{9} \sin 3x$ $I_0^{2\pi} = \left[\frac{-x}{3} \cos 3x + \frac{1}{9} \sin 3x \right]_0^{2\pi}$ $= \left[\frac{-2\pi}{3} \cos 6\pi + \frac{1}{9} \sin 6\pi \right] - \left[0 + \frac{1}{9} \sin 0 \right]$ $= \frac{-2\pi}{3}$ | 5 | <p>1 evidence of integration by parts</p> <p>1 correct choice of u, dv</p> <p>1 correct substitution</p> <p>1 final integration correct</p> <p>1 evaluation</p> |

| Question | | Expected Answer(s) | Max Mark | Additional Guidance |
|----------|----------|--|----------|---|
| B | 4 | $\sum_{r=1}^{80} 3r^2 = 3 \sum_{r=1}^{80} r^2$ <p>using $\sum_{r=1}^n r^2 = \frac{n(n+1)(2n+1)}{6}$ *</p> $3 \sum_{r=1}^{80} r^2 = 3 \left(\frac{80(81)(2 \cdot 80 + 1)}{6} \right)$ $= 521,640$ | 2 | <p>1 correct substitution into *</p> <p>1 evaluation (using incorrect formula – this mark available if of equivalent difficulty eg</p> $\sum_{r=1}^n r^2 = \left(\frac{n(n+1)}{2} \right)^2$ |
| B | 5 | (a) $(e^x + 2)^4$ $= 1 \cdot (e^x)^4 (2)^0 + 4(e^x)^3 (2)^1 + 6(e^x)^2 (2)^2$ $+ 4(e^x)^1 (2)^3 + 1 \cdot (e^x)^0 (2)^4$ $= e^{4x} + 8e^{3x} + 24e^{2x} + 32e^x + 16$ | 3 | <p>Accept Binomial expansion <i>or</i> Pascal's Triangle</p> <p>1 correct coefficients</p> <p>1 correct powers of e^x and 2</p> <p>1 simplification</p> |
| B | 5 | (b) $\int (e^x + 2)^4 dx$ $= \int (e^{4x} + 8e^{3x} + 24e^{2x} + 32e^x + 16) dx$ $= \frac{e^{4x}}{4} = \frac{8e^{3x}}{3} + \frac{24e^{2x}}{2} + 32e^x + 16x + c$ | 2 | <p>1 correct integration of composite function (at least one correct term involving composite exponential)</p> <p>1 completion of integral (+ c not essential)</p> |

| Question | | | Expected Answer(s) | Max Mark | Additional Guidance |
|----------|----------|------------|---|----------|---|
| B | 6 | (a) | 10 000 people. | 1 | |
| B | 6 | (b) | $\frac{10000}{N(20000 - N)} = \frac{A}{N} + \frac{B}{20000 - N}$ $10\,000 = A(20\,000 - N) + BN$ $A = \frac{1}{2}, \quad B = \frac{1}{2}$ <p>Using $\frac{10000}{N(20000 - N)} dN = dt$</p> <p>gives $\frac{1}{2} \left(\frac{1}{N} + \frac{1}{20000 - N} \right) dN = dt$</p> <p>Integrating,</p> $\int \left(\frac{1}{N} + \frac{1}{20000 - N} \right) dN = \int 2 dt$ $\ln N - \ln(20000 - N) = 2t + c$ $\ln \frac{N}{20000 - N} = 2t + c$ | 5 | <p>1 appropriate form of partial fractions</p> <p>1 correct values of A and B</p> <p>1 separate variables</p> <p>1 starts integration eg $\int \frac{1}{N} dN$ correct</p> <p>1 completes integration (moduli signs not required)</p> |

| Question | | | Expected Answer(s) | Max Mark | Additional Guidance |
|----------|----------|-----|---|----------|---|
| B | 6 | (c) | <p>Using $\ln \frac{N}{20000 - N} = 2t + c$</p> <p>gives $\frac{N}{20000 - N} = e^{2t+c}$</p> $\frac{N}{20000 - N} = Ke^{2t} \text{ (where } K = e^c \text{)}$ <p>When $t = 0, N = 100$</p> $\frac{100}{19900} = K$ $K = \frac{1}{199}$ <p>Hence $N = (20000 - N) \frac{e^{2t}}{199}$</p> $199N = (20000 - N)e^{2t}$ $N(199 + e^{2t}) = 20000e^{2t}$ $N = \frac{20000e^{2t}}{199 + e^{2t}}$ | 4 | <p>1 accurately converts to exponential form (stating explicitly $K = e^c$ not required)</p> <p>1 interprets initial condition</p> <p>1 K value</p> <p>1 correctly gathers N terms</p> |

[END OF SECTION B]

[END OF QUESTION PAPER]